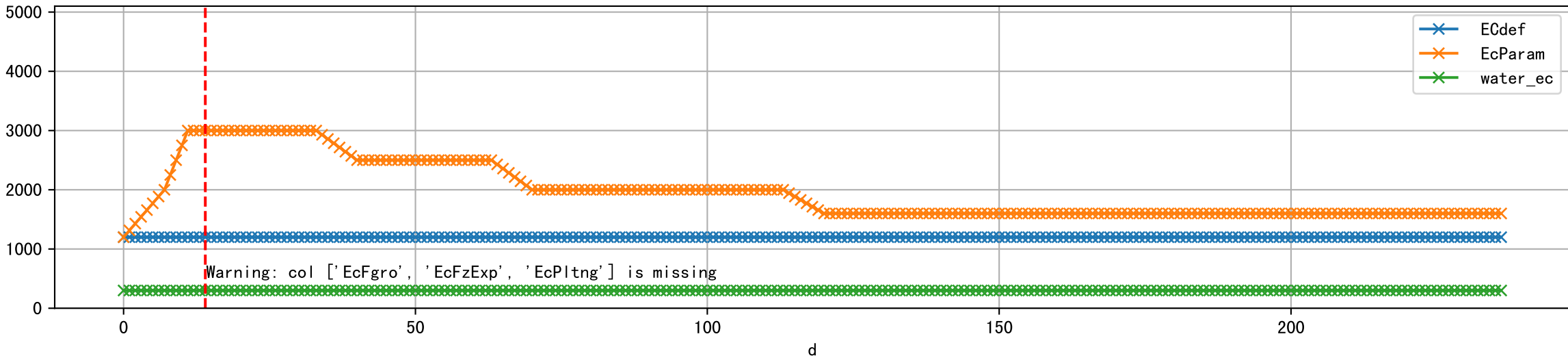
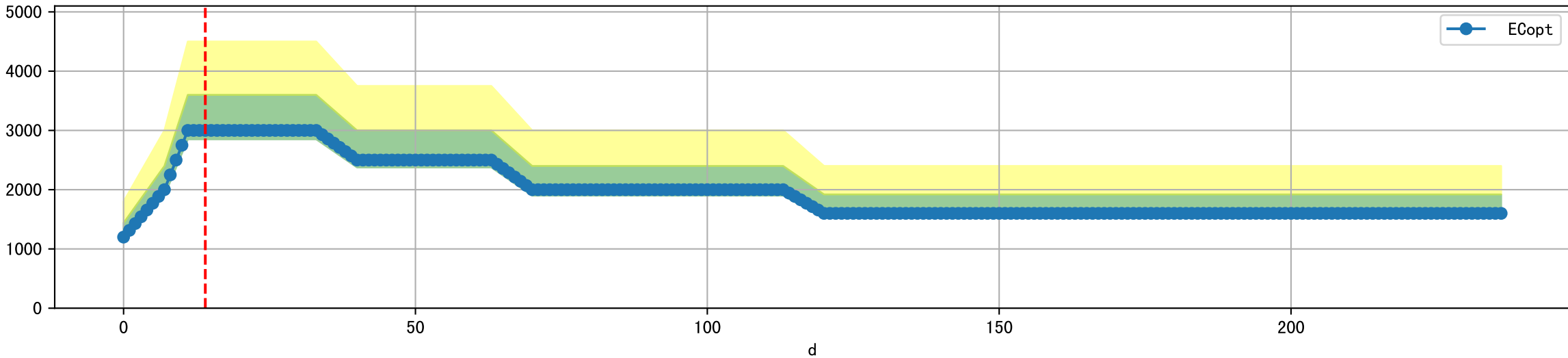


FgArea: [' 2' ]  
NJ15 L1  
2025-10-20 (Day 14)

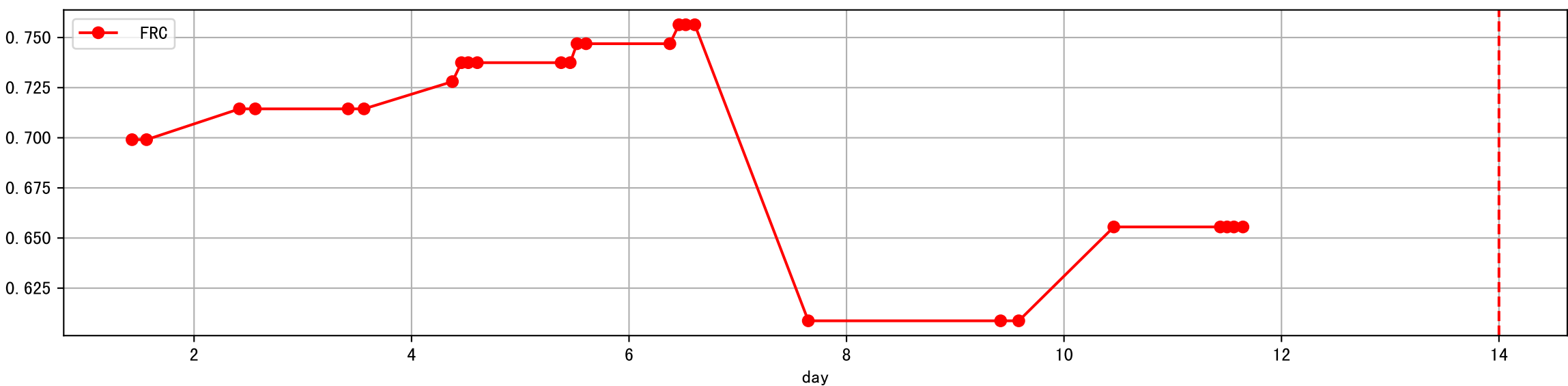
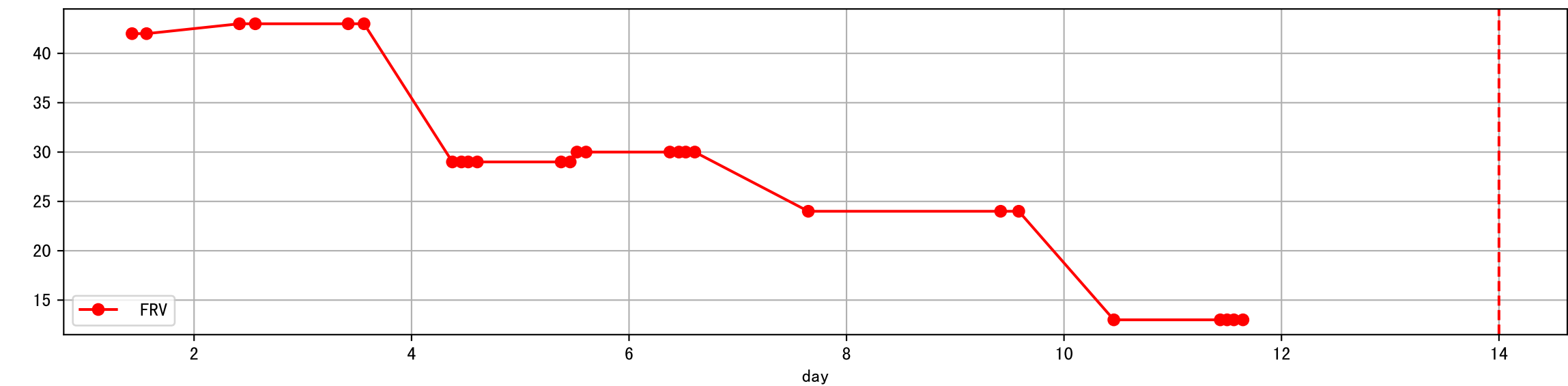
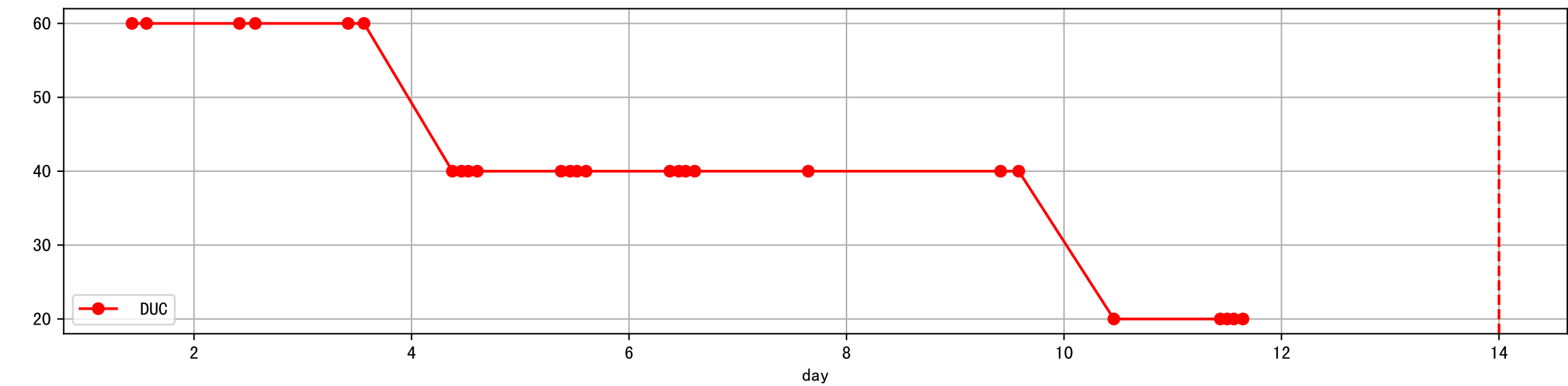
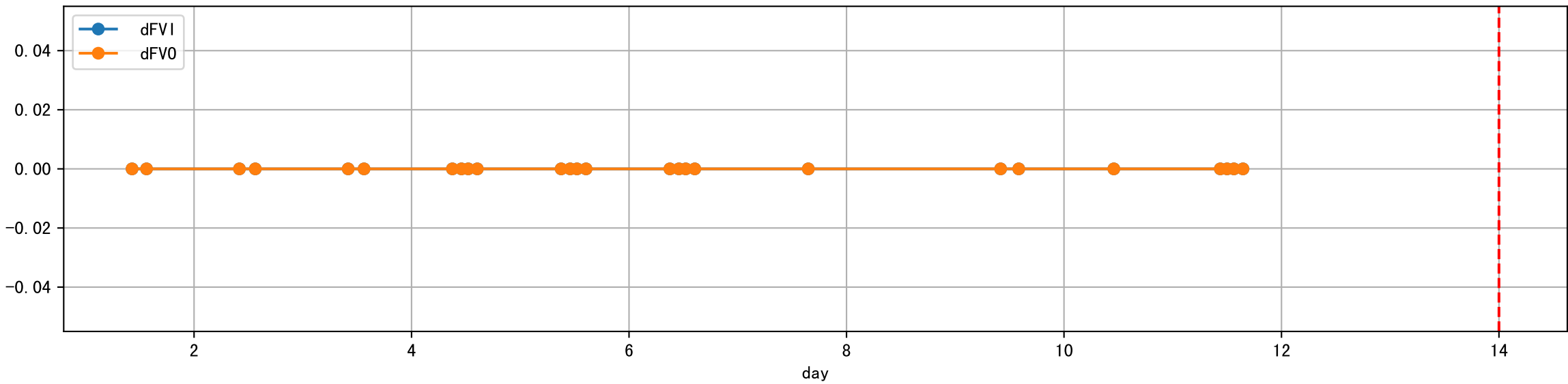
Plot [['EcFgro', 'EcFzExp', 'EcPltng', 'ECdef', 'EcParam', 'water\_ec']]

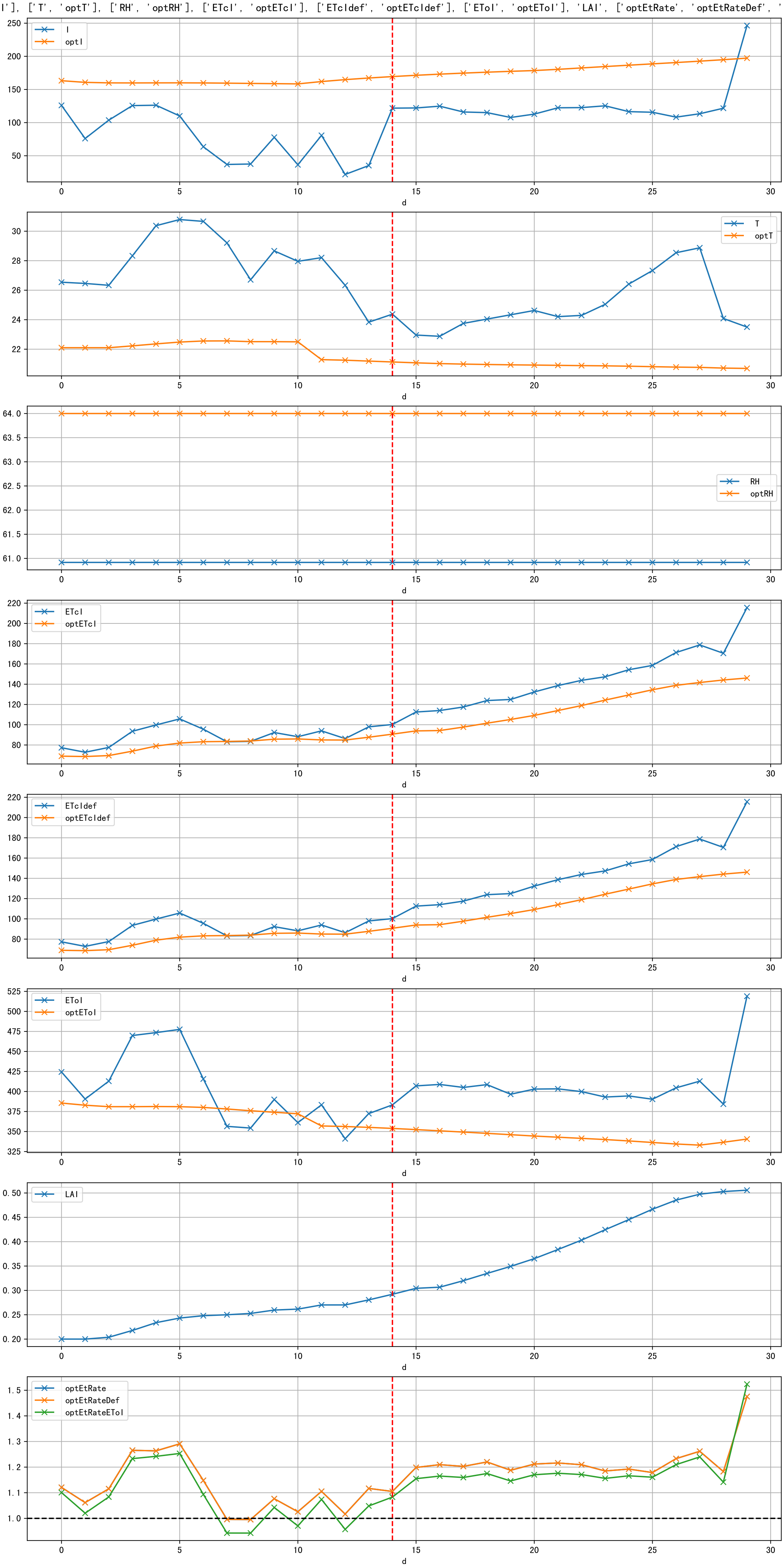


Plot [' ECopt ']

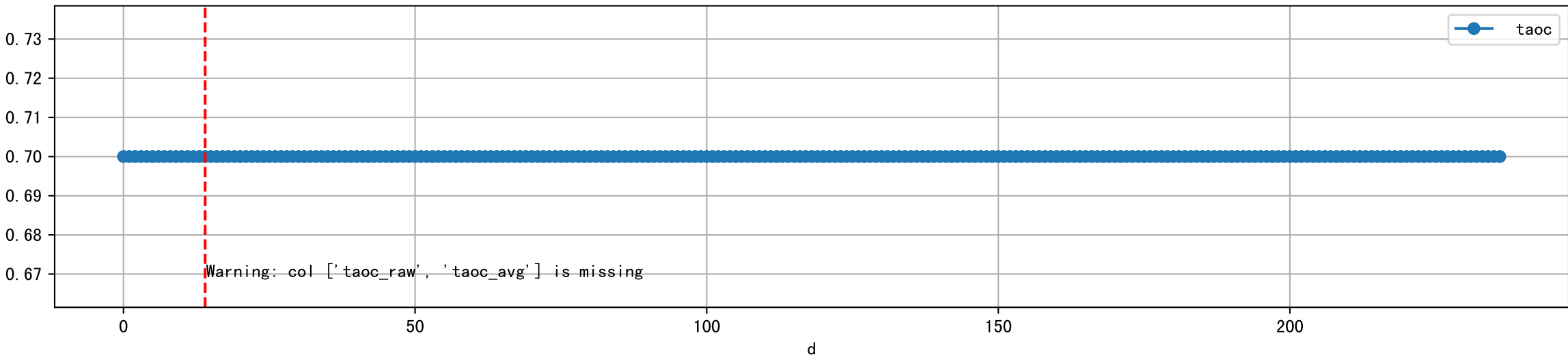


Plot Sensor and FgRec Data

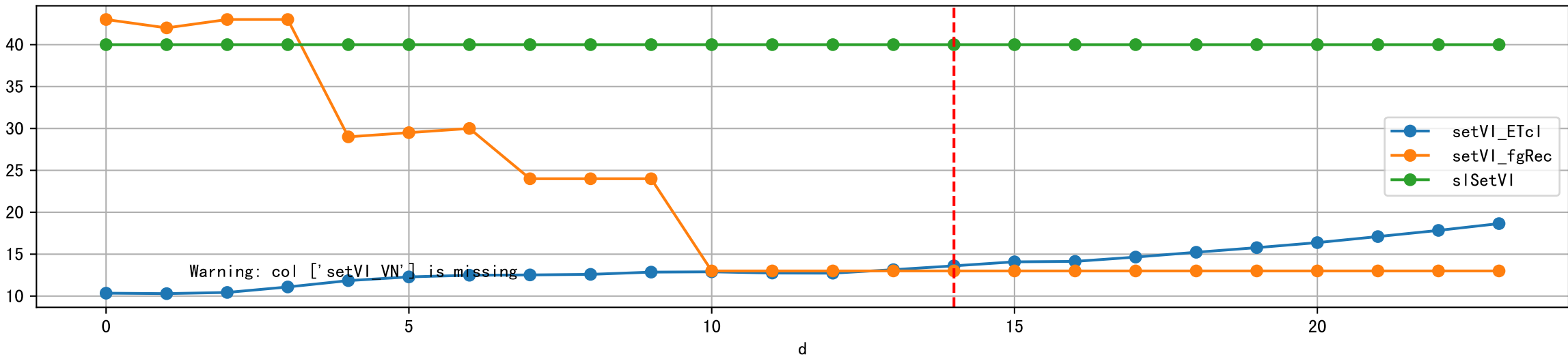




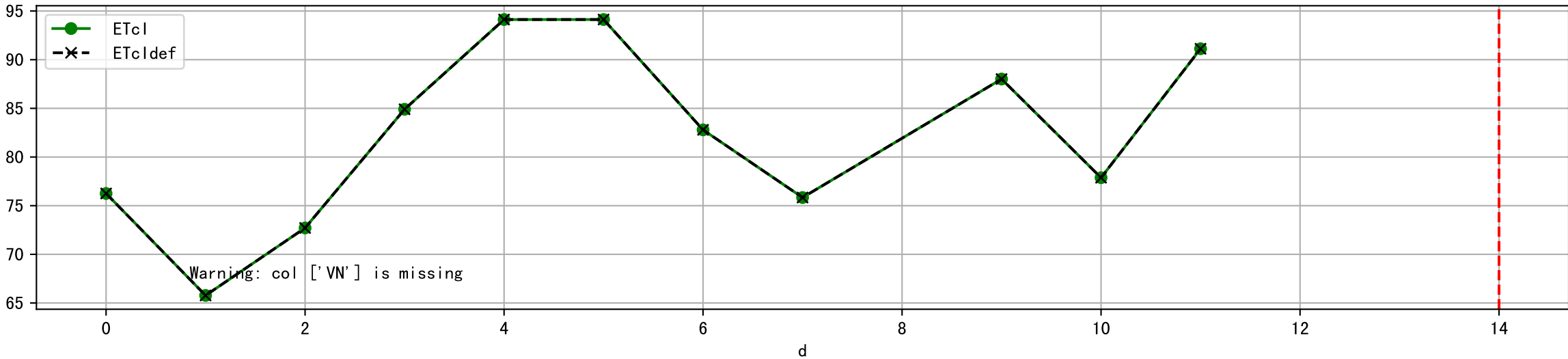
Plot [['taoc', 'taoc\_raw:ro', 'taoc\_avg:r-']]

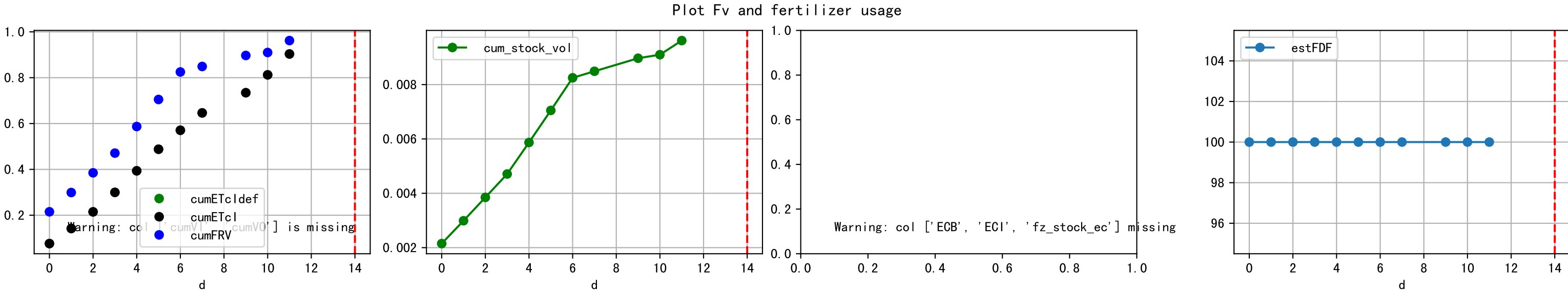


Plot [['setVI\_ETcl', 'setVI\_fgRec', 'setVI\_VN', 'sISetVI']]

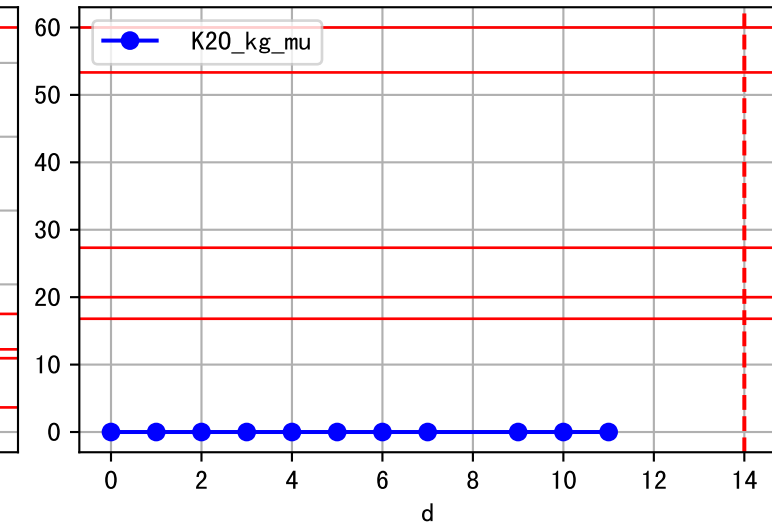
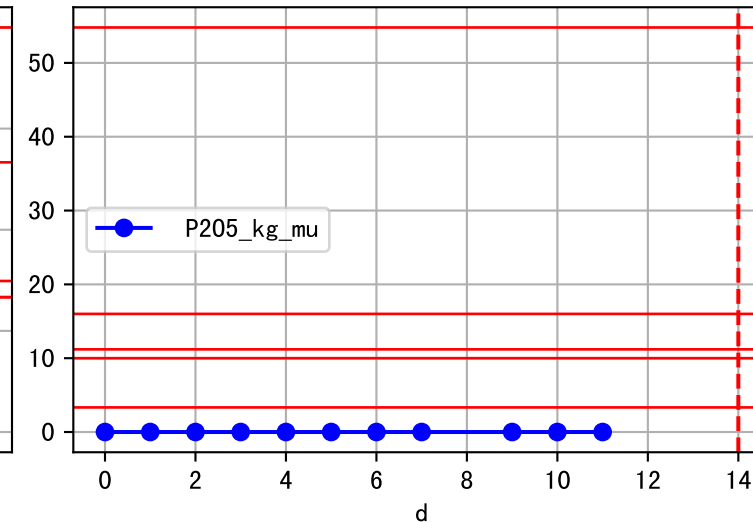
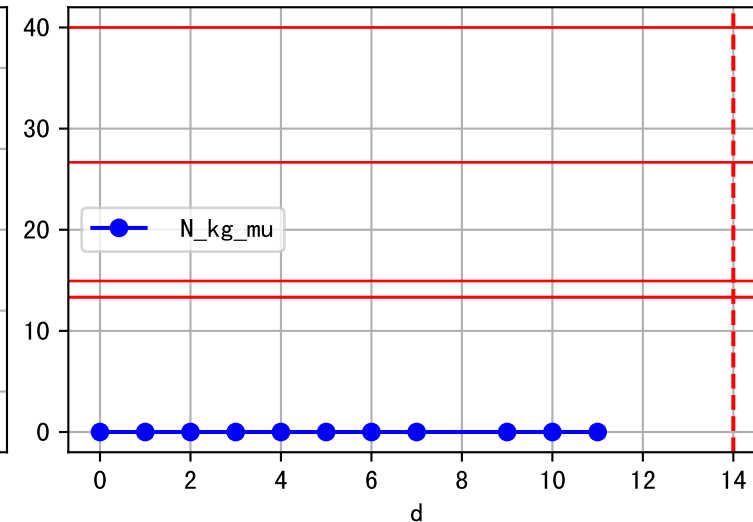
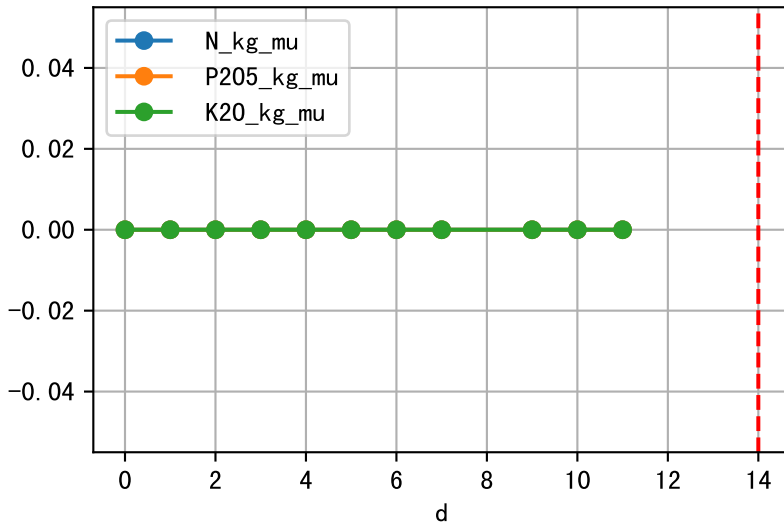


Plot ET/VN

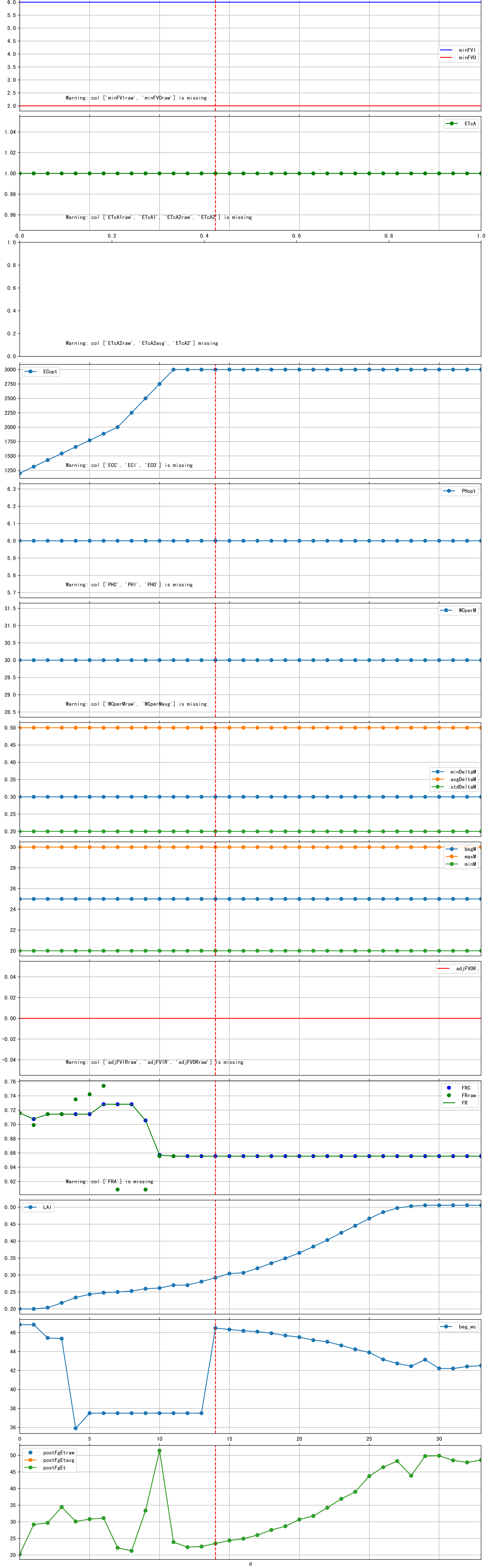




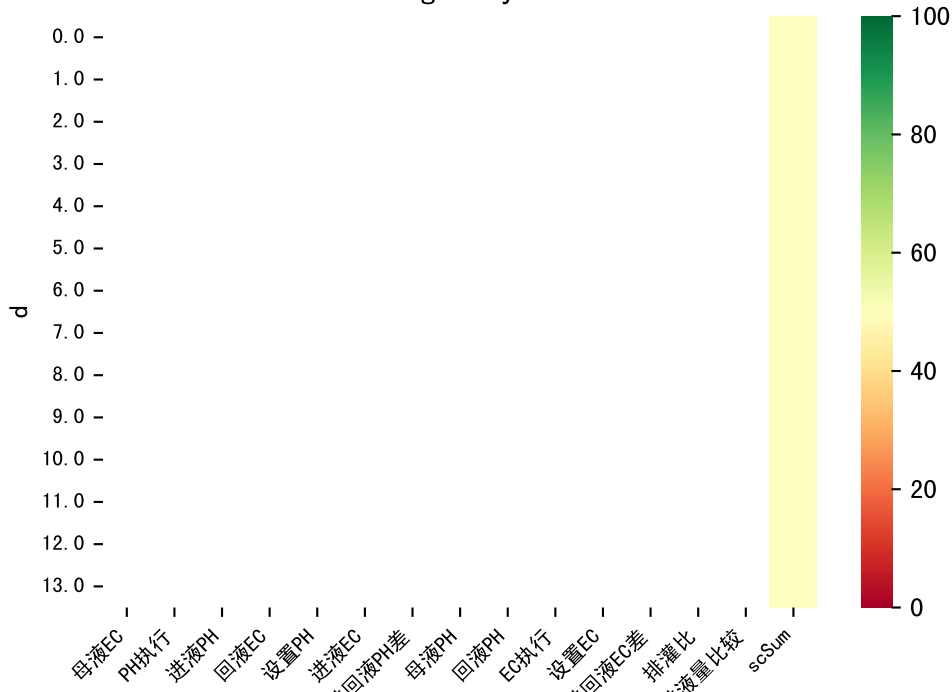
Fertilizer Range Source: kerleyL, kerleyH, UnivFL, TNAI, Haifa

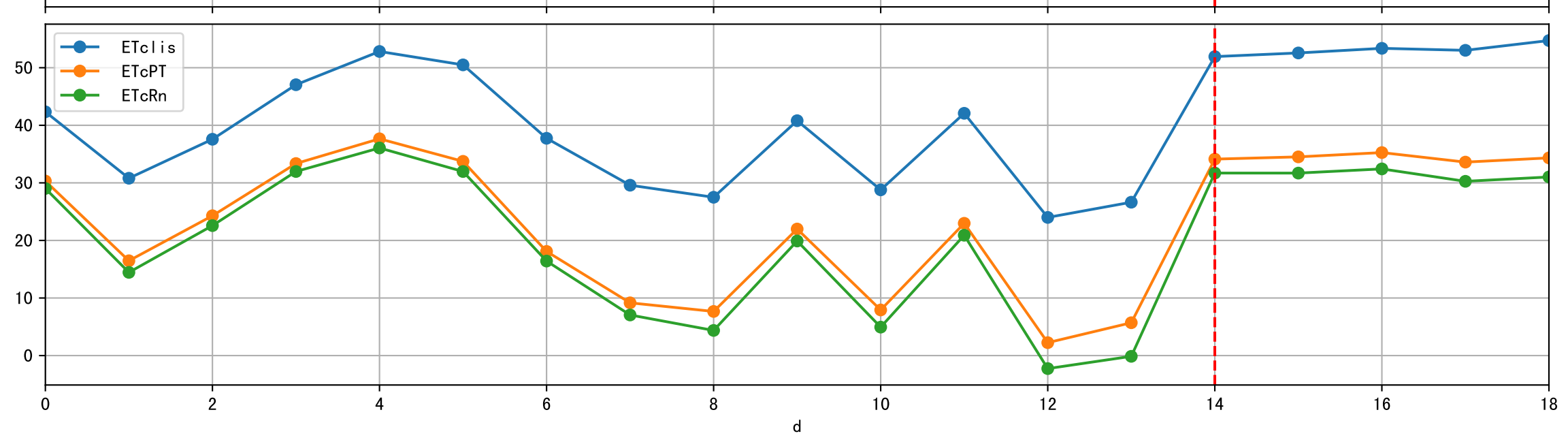
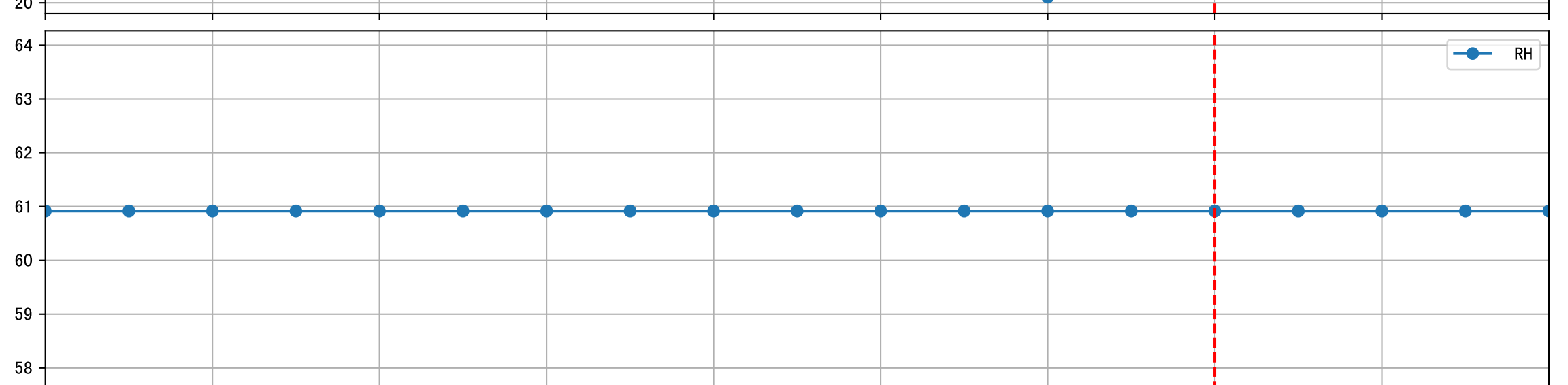
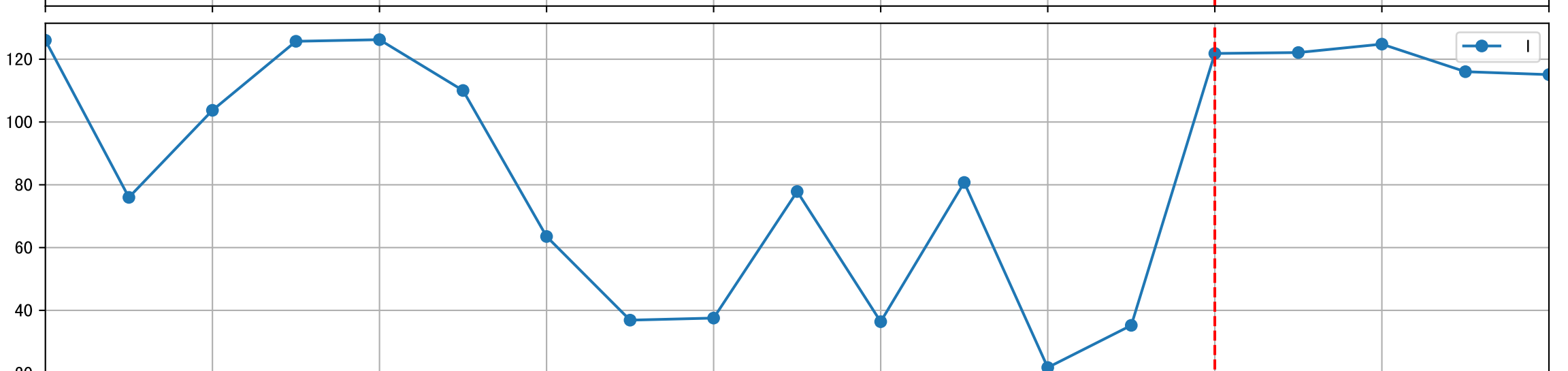
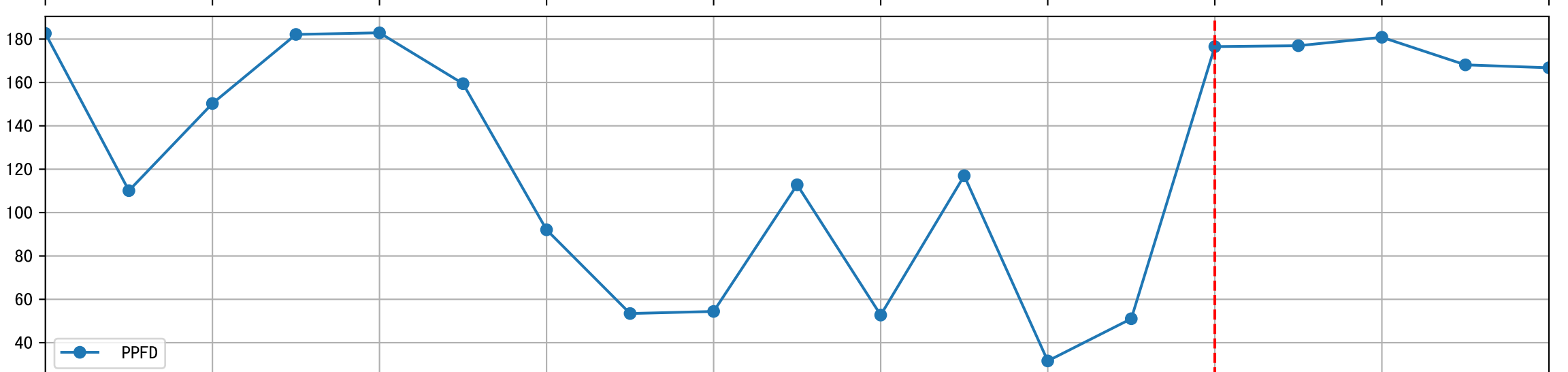
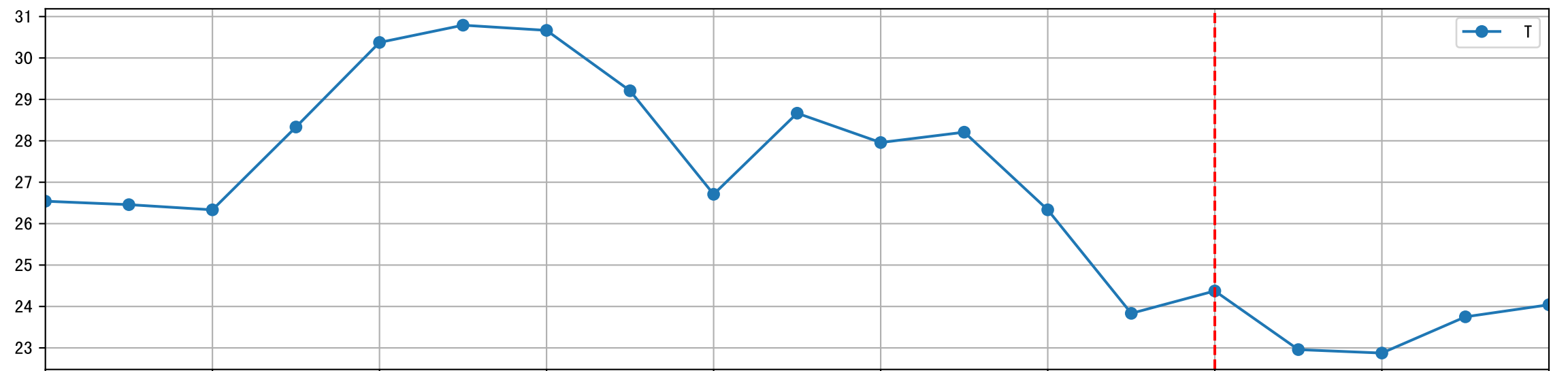
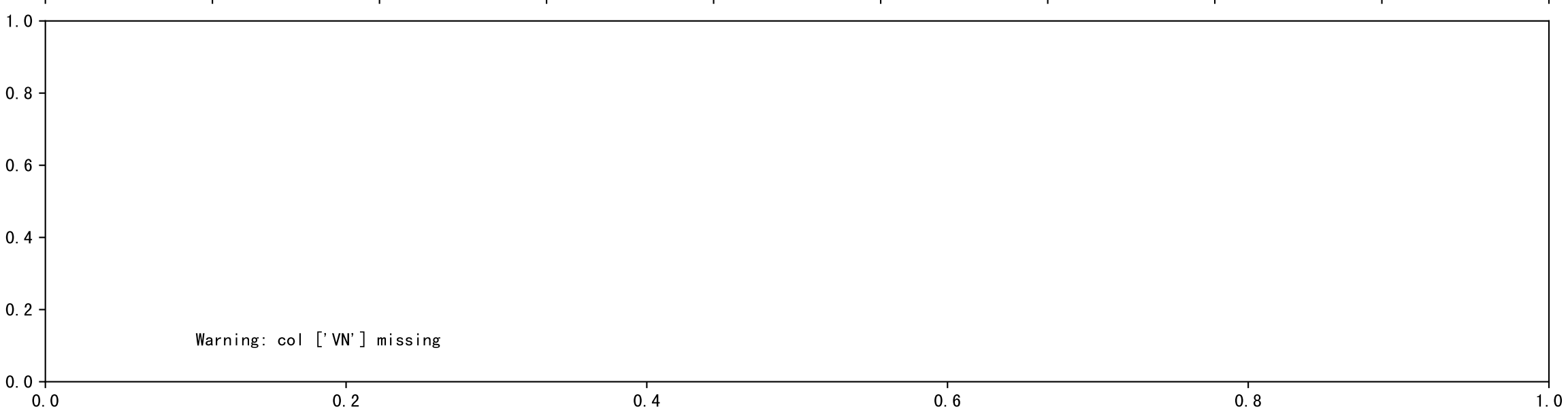
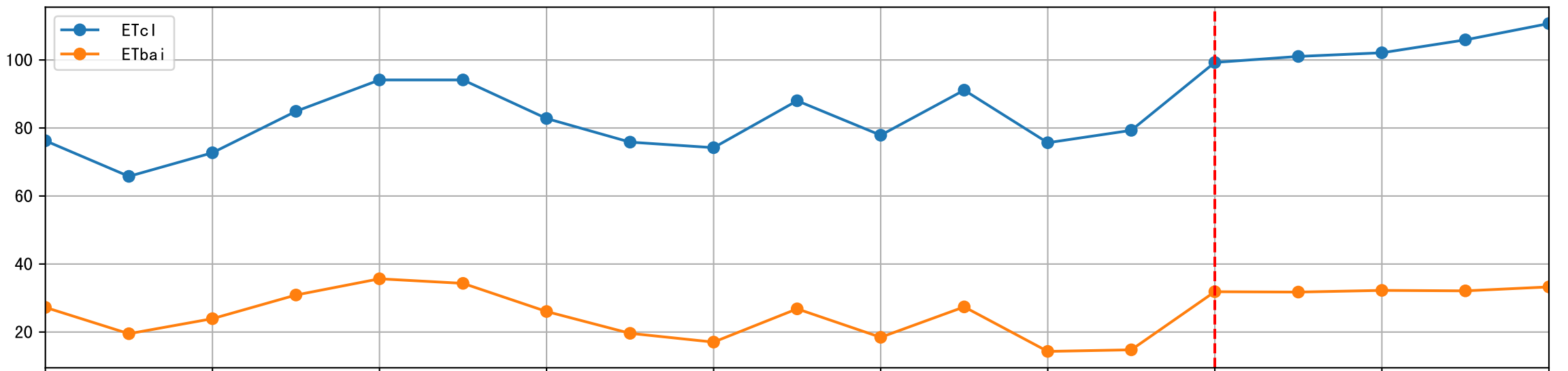


Trend plot for L1A2\_2

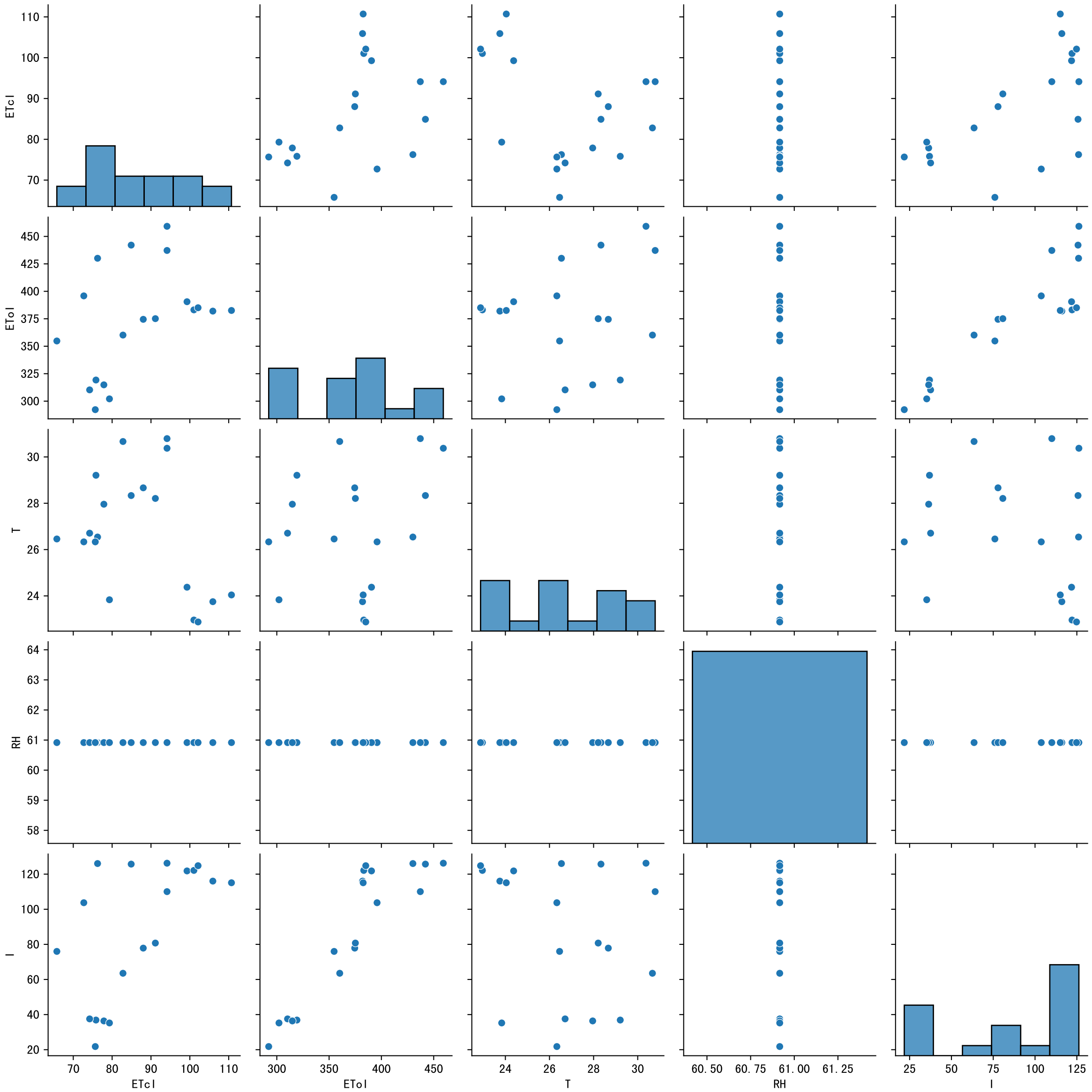


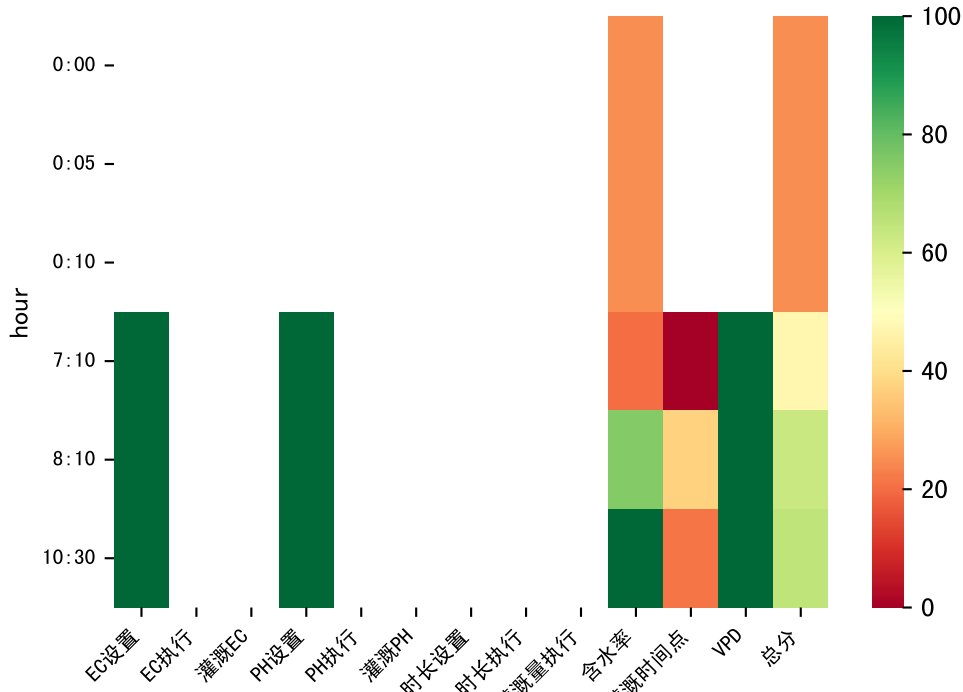
# FgDaily





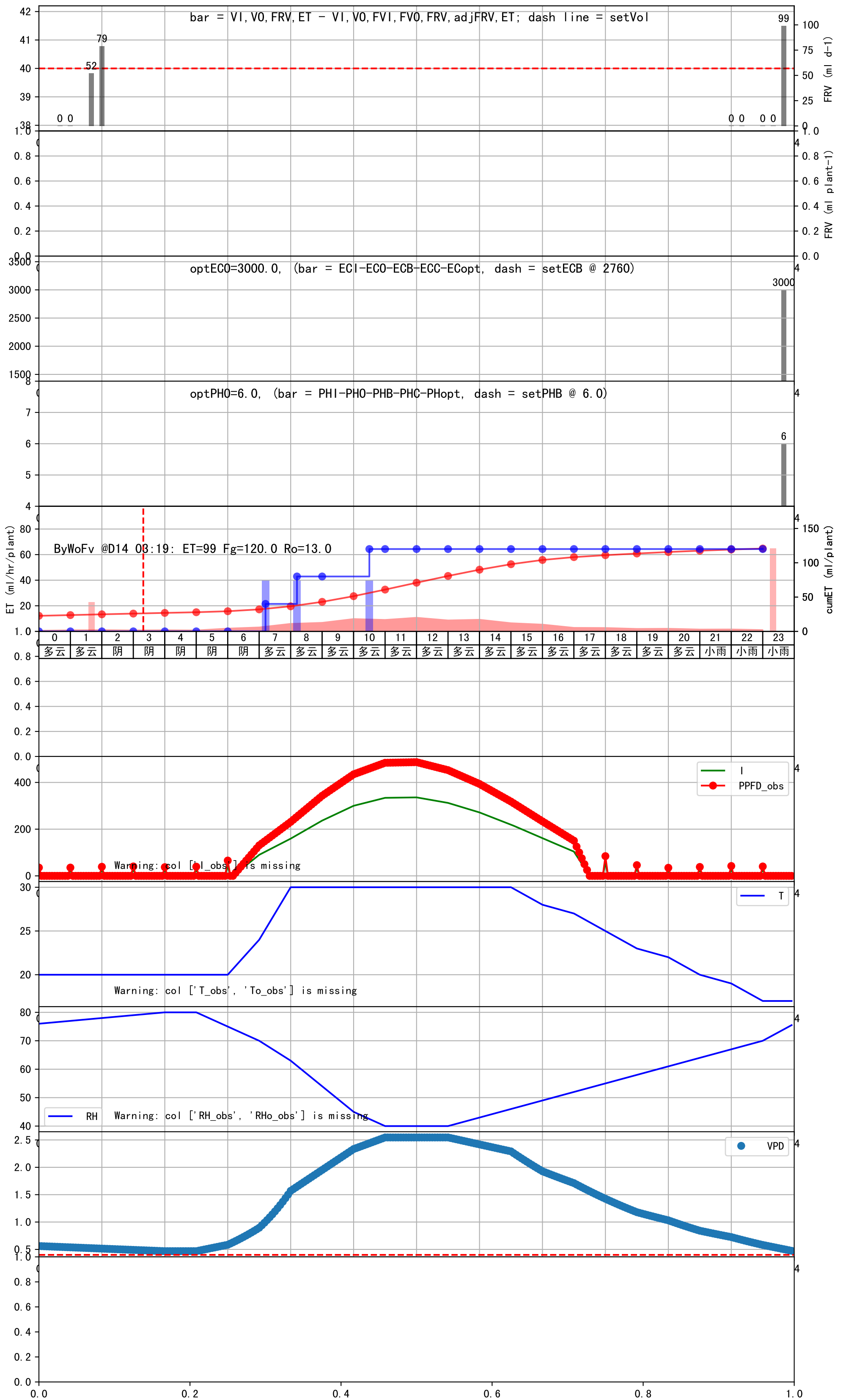


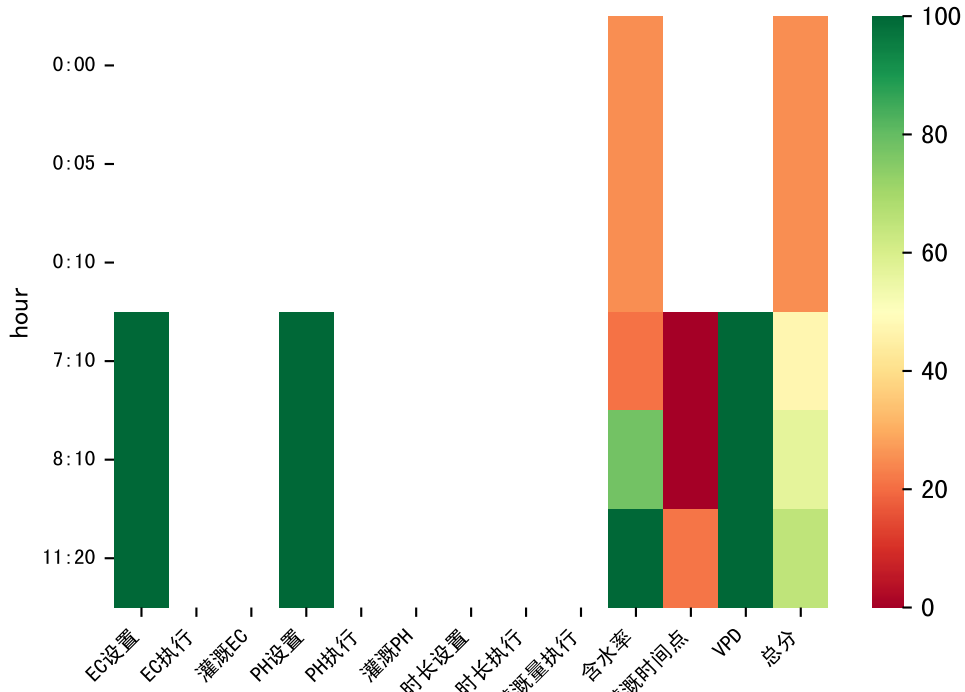




L1A2

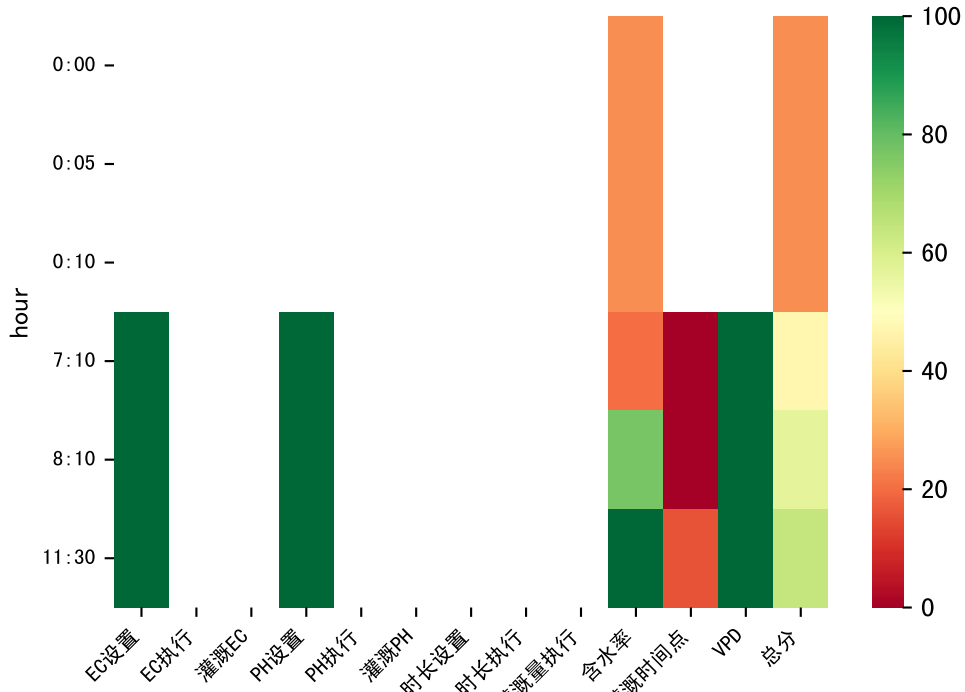
时间	灌溉时长(秒)	灌溉量(毫升/株)	灌溉总量(方/次)	天气	注释
07:10	61	40.0	0.163	多云	预期@07:10 手动 (未用传感器)
08:10	61	40.0	0.163	多云	预期@08:10 手动 (未用传感器)
10:30	61	40.0	0.163	多云	预期@10:30 手动 (未用传感器)
总计	183.0 (3次)	120.0			建议进液EC: 2760, PH: 6.0





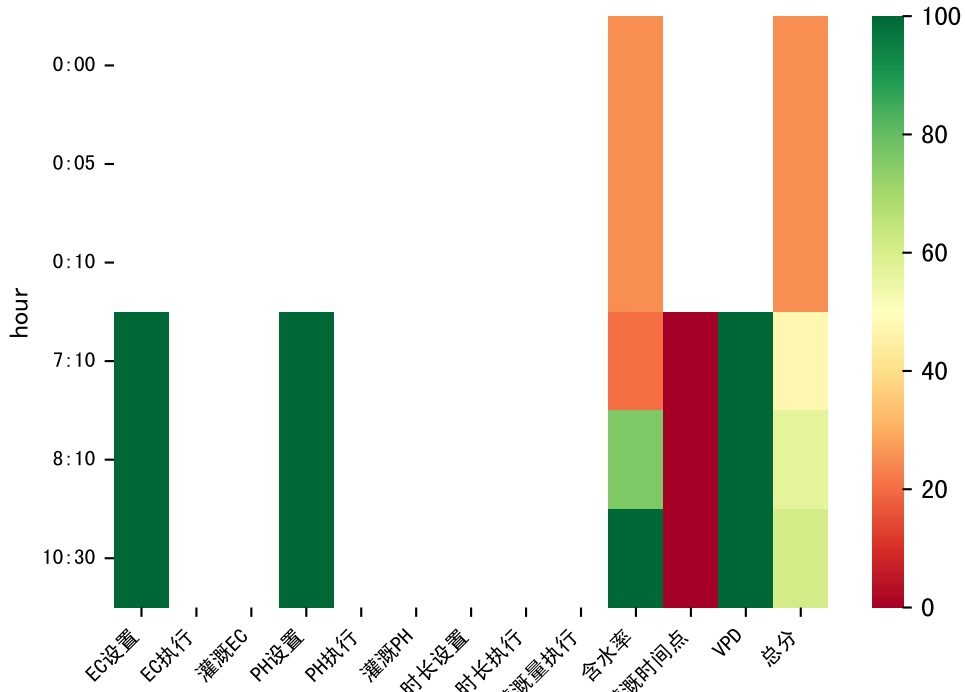
时间	灌溉时长(秒)	灌溉量(毫升/株)	灌溉总量(方/次)	天气	注释
07:10	61	40.0	0.163	大雨	假设@07:10 未知程序(未用传感器)
08:10	61	40.0	0.163	阴	假设@08:10 未知程序(未用传感器)
11:20	61	40.0	0.163	小雨	假设@11:20 未知程序(未用传感器)
总计	183.0 (3次)	120.0			建议进液EC: 3230, PH: 6.0



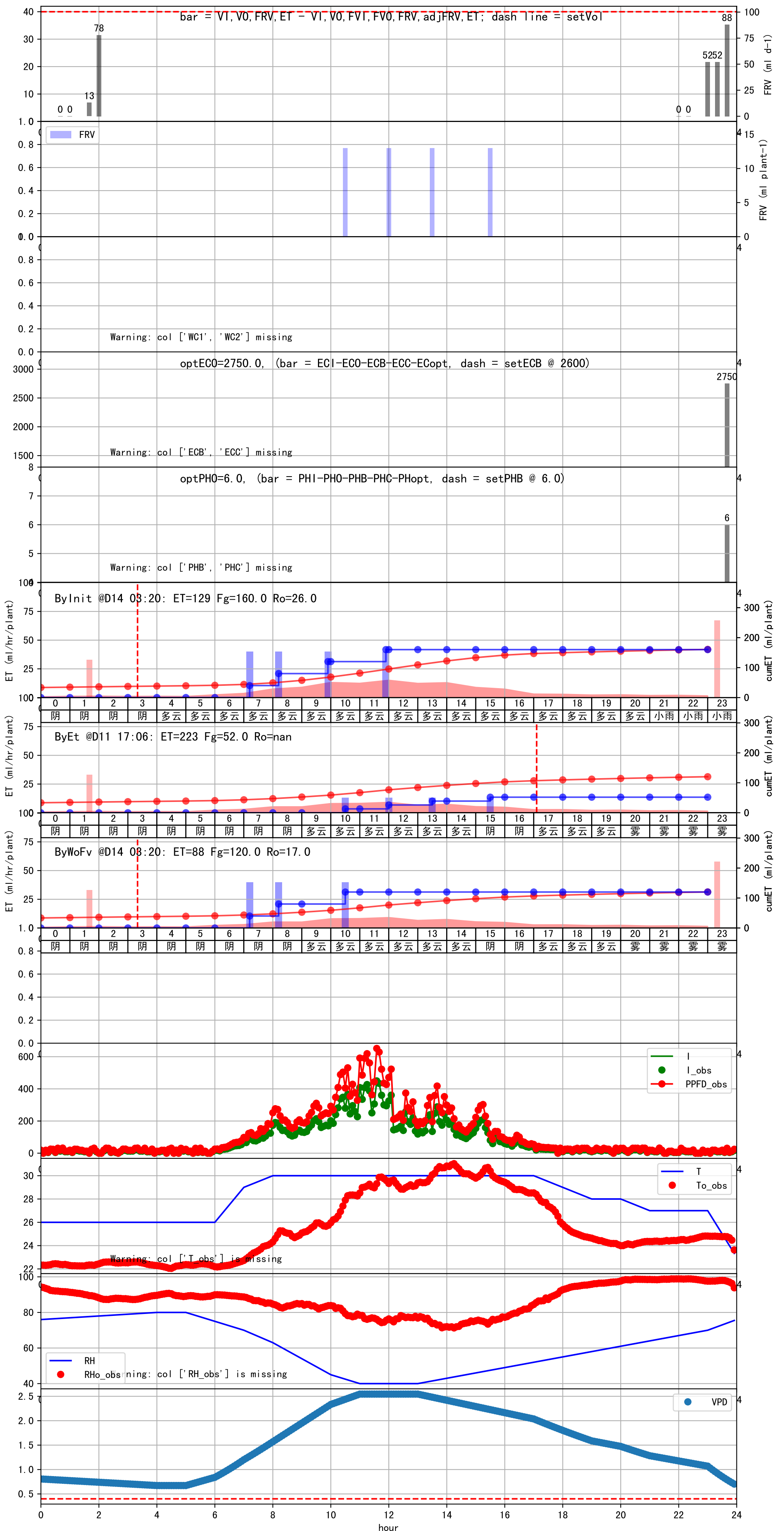


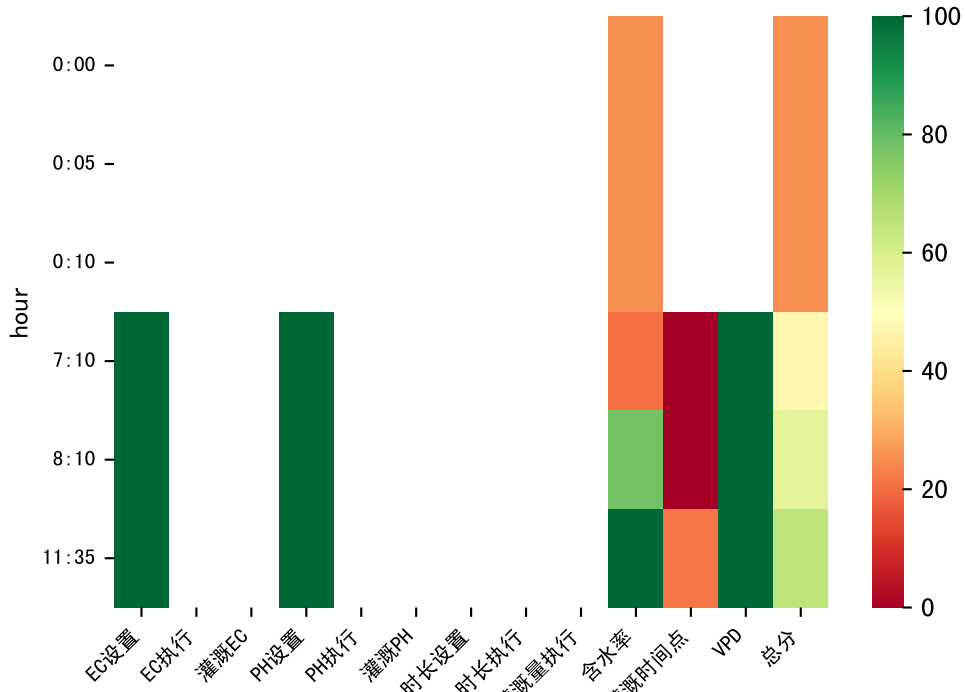
时间	灌溉时长(秒)	灌溉量(毫升/株)	灌溉总量(方/次)	天气	注释
07:10	61	40.0	0.163	阴	假设@07:10 未知程序(未用传感器)
08:10	61	40.0	0.163	雾	假设@08:10 未知程序(未用传感器)
11:30	61	40.0	0.163	阴	假设@11:30 未知程序(未用传感器)
总计	183.0 (3次)	120.0			建议进液EC: 3350, PH: 6.0





时间	灌溉时长(秒)	灌溉量(毫升/株)	灌溉总量(方/次)	天气	注释
07:10	20	40.0	0.163	阴	假设@07:10 手动 (未用传感器)
08:10	20	40.0	0.163	阴	假设@08:10 手动 (未用传感器)
10:30	20	40.0	0.163	多云	假设@10:30 手动 (未用传感器)
总计	60.0 (3次)	120.0			建议进液EC: 2600, PH: 6.0





时间	灌溉时长(秒)	灌溉量(毫升/株)	灌溉总量(方/次)	天气	注释
07:10	20	40.0	0.163	雾	假设@07:10 手动 (未用传感器)
08:10	20	40.0	0.163	雾	假设@08:10 手动 (未用传感器)
11:35	20	40.0	0.163	雾	假设@11:35 手动 (未用传感器)
总计	60.0 (3次)	120.0			建议进液EC: 2760, PH: 6.0

